

# Extending the Integrated Laplace Approximation (using MCMC)

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The Integrated Nested Laplace Approximation provides a feasible framework for approximate Bayesian inference. However, the type of models that can be fitted in practice is constrained to those implemented in the **R-INLA** package. We describe here a novel approach to fit more general models by combining MCMC and INLA.

## Extending INLA (using MCMC)

- Bivand et al. (2014, 2015) provide a way to extend the models that can be fitted with **R-INLA**:
  - Fix one or several hyperparameters so that the model can be fitted with **R-INLA**
  - Fit these conditional models for different values of the fixed hyperparameters
  - Combine the resulting models using Bayesian Model Averaging (BMA)
- Using a regular grid of values of the hyperparameters may not be feasible:
  - Unbounded parameters
  - Large number of parameters
- Split the vector of parameters  $\theta = (\theta_c, \theta_{-c})$ 
  - Models can be fitted with **R-INLA** conditioning on  $\theta_c$
- General idea:
  - Use MCMC to estimate  $\pi(\theta_c|y)$
  - Use **R-INLA** to estimate  $\pi(\theta_{-c}|\theta_c, y)$
  - Use BMA to obtain  $\pi(\theta_{-c}|y)$

## Metropolis-Hastings with INLA

- Step (n) in M-H requires:
  - Sampling a new proposal  $\theta_c^{(n)}$  from  $q(\cdot|\theta_c^{(n-1)})$
  - Fitting conditional model:  $\pi(\theta_{-c}|y, \theta_c^{(n)})$  and  $\pi(y|\theta_c^{(n)})$
  - Accept/reject  $\theta_c^{(n)}$ ; requires  $\pi(y|\theta_c^{(n-1)})$  and  $\pi(y|\theta_c^{(n)})$
$$\frac{\pi(\theta_c^{(n)}|y)q(\theta_c^{(n-1)}|\theta_c^{(n)})}{\pi(\theta_c^{(n-1)}|y)q(\theta_c^{(n)}|\theta_c^{(n-1)})} = \frac{\pi(y|\theta_c^{(n)})\pi(\theta_c^{(n)})q(\theta_c^{(n-1)}|\theta_c^{(n)})}{\pi(y|\theta_c^{(n-1)})\pi(\theta_c^{(n-1)})q(\theta_c^{(n)}|\theta_c^{(n-1)})}$$
- Output is:
  - Sample from  $\theta_c|y$
  - List of fitted models (with conditional marginals for the other parameters)
$$\left\{ \pi(\theta_{-c}|y, \theta_c^{(i)}) \right\}_{i=1}^k$$
- Marginals are obtained as follows:
  - $\pi(\theta_c|y)$  from the MCMC output
  - $\pi(\theta_{-c}|y)$  by BMA'ing  $\left\{ \pi(\theta_{-c}|y, \theta_c^{(i)}) \right\}_{i=1}^k$

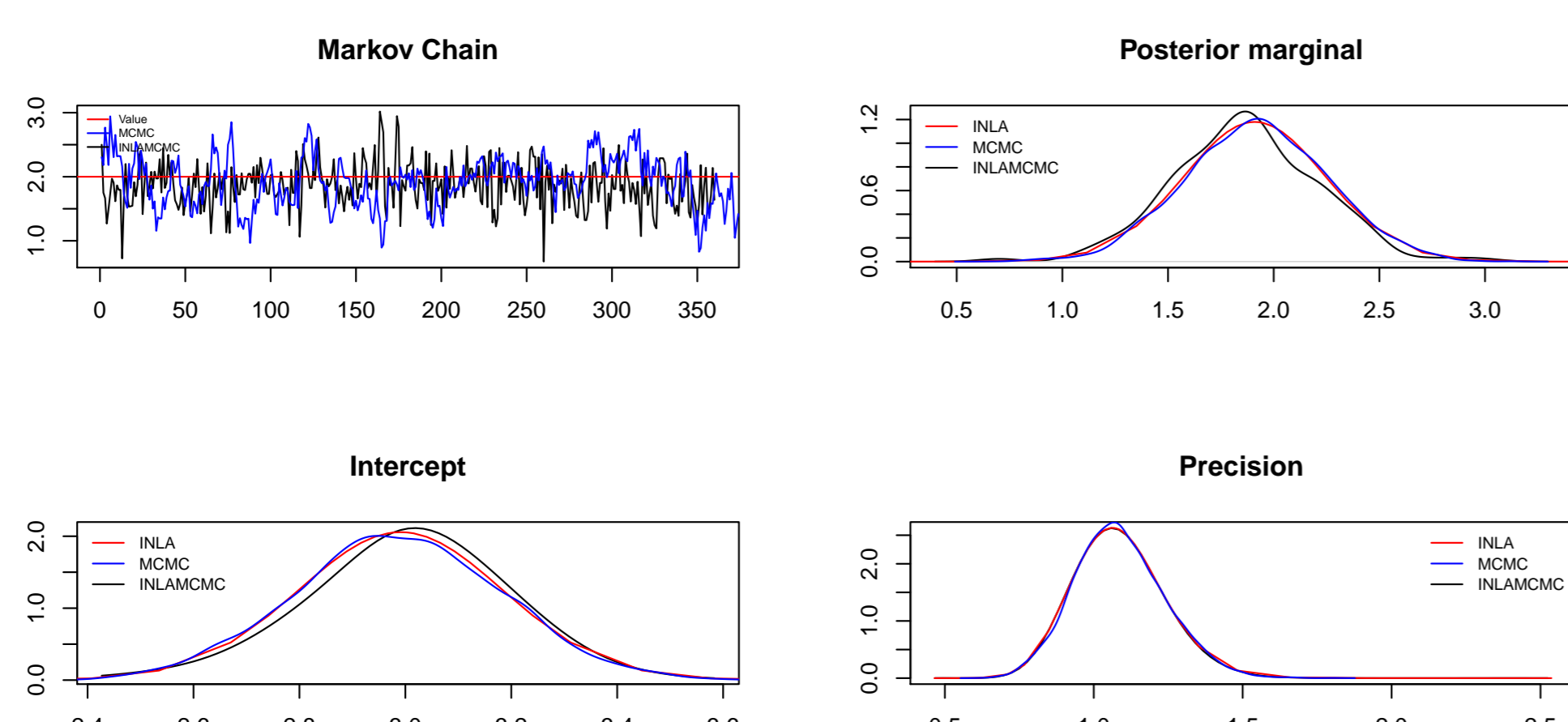
## Toy Example: Univariate Case

- Simple linear regression with one covariate:

$$y_i = \alpha + \beta x_i + \varepsilon_i; \quad i = 1, \dots, 100$$

Here,  $\varepsilon_i$  is a Gaussian error term with zero mean and precision  $\tau$ .

- $\beta$  is sampled using M-H
- $\pi(\beta|y)$  is computed from sampled values
- $\alpha, \tau$  are estimated with **R-INLA**
- $\pi(\alpha|y), \pi(\tau|y)$  are computed by BMA'ing the fitted models
- We have computed the posterior marginals of the parameters in 3 different ways:
  - R-INLA
  - MCMC
  - INLA+MCMC



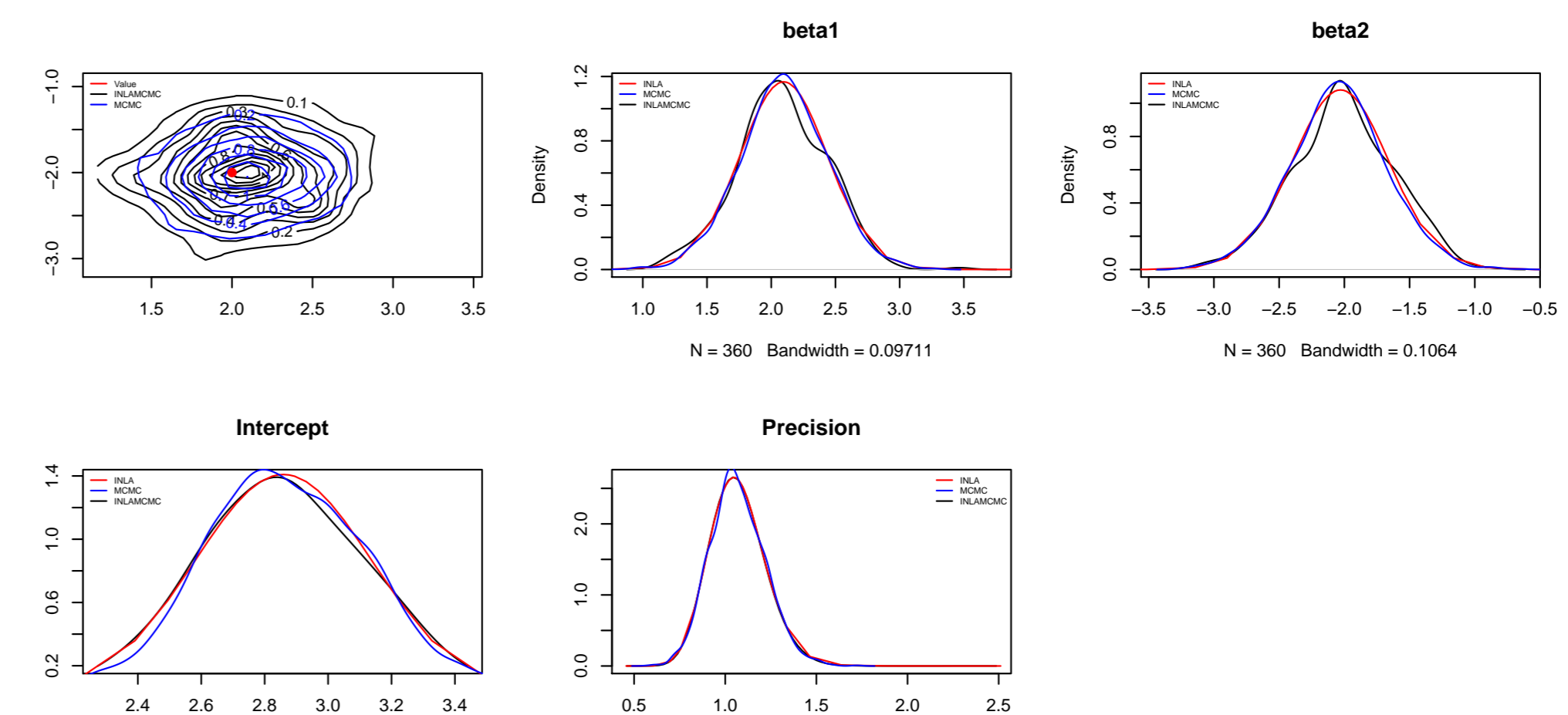
## Toy Example: Bivariate Case

- Simple linear regression with two covariate:

$$y_i = \alpha + \beta_1 x_{1i} + \beta_2 x_{2i} + \varepsilon_i; \quad i = 1, \dots, 100$$

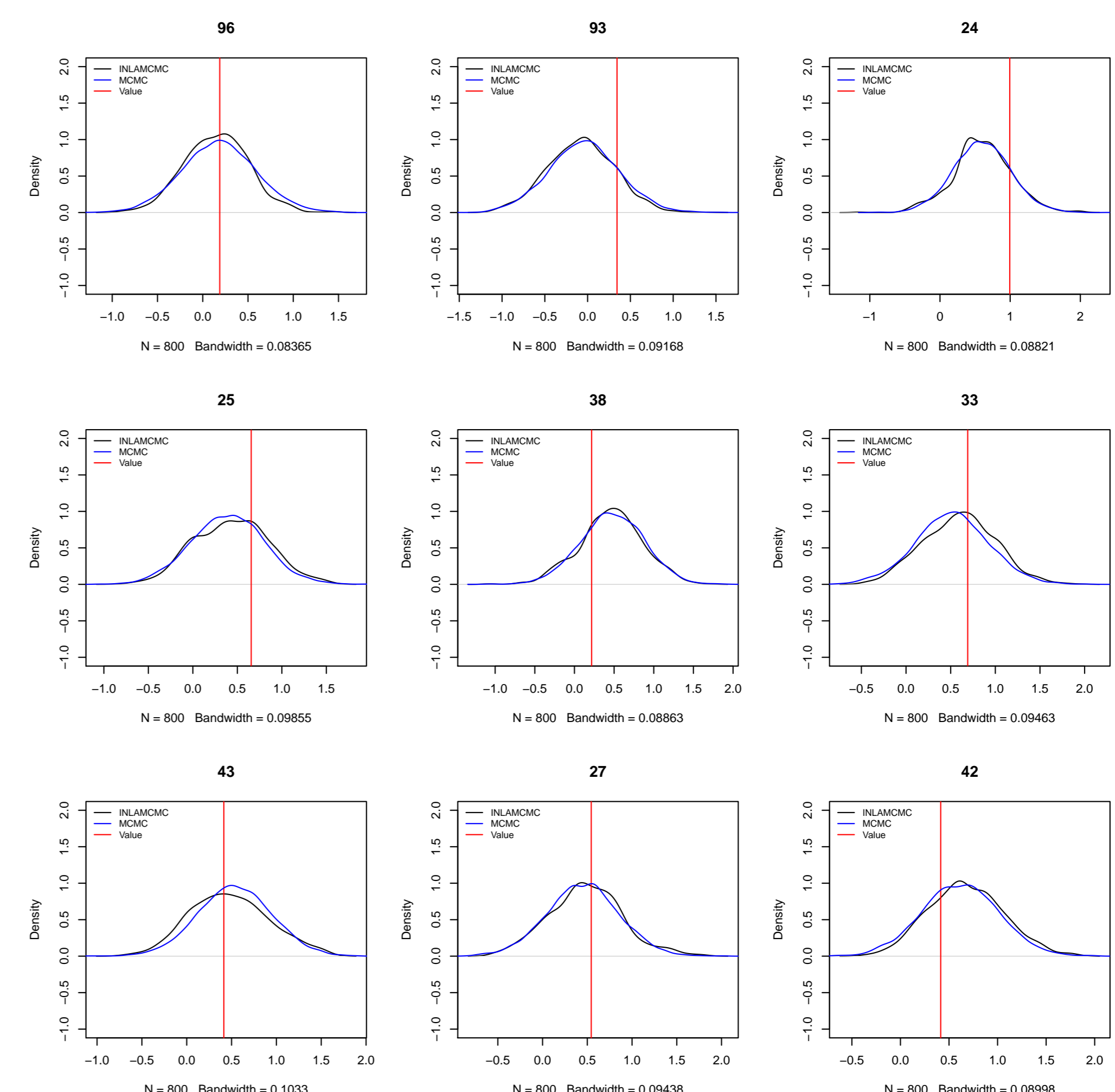
Here,  $\varepsilon_i$  is a Gaussian error term with zero mean and precision  $\tau$ .

- $\beta_1, \beta_2$  are sampled using M-H
- $\pi(\beta_i|y); \quad i = 1, 2$  are computed from sampled values
- $\pi(\beta_1, \beta_2|y)$  can be estimated from sampled values
- $\alpha, \tau$  are estimated with **R-INLA**
- $\pi(\alpha|y), \pi(\tau|y)$  are computed by BMA'ing the fitted models
- We have computed the posterior marginals of the parameters in 3 different ways:
  - R-INLA
  - MCMC
  - INLA+MCMC



## Toy Example: Imputation of Missing Covariates

- Simple linear regression with one covariate
- Missing values in the covariates
- In principle, **R-INLA** cannot handle this...
- We treat missing values as model parameters
- Missing covariates  $x_m$  are sampled using block updating in M-H
- $\pi(x_m|y)$  is computed from sampled values
- $\beta_1, \tau$  are estimated with **R-INLA**
- $\pi(\beta_1|y), \pi(\tau|y)$  are computed by BMA'ing the fitted models
- We have computed the posterior marginals of the parameters in 2 different ways:
  - MCMC
  - INLA+MCMC



Work in progress. We hope to apply this new approach to:

- Models with complex structures of the random effects that involve several hyperparameters
- Models with a hierarchical structure on the hyperparameters (for example, the precision)
- Spatial econometrics models that include several spatial autocorrelation parameters
- Imputation of missing covariates in real datasets

To download code and references, please visit:

<http://www.uclm.es/profesorado/vgomez/INLAMCMC>

